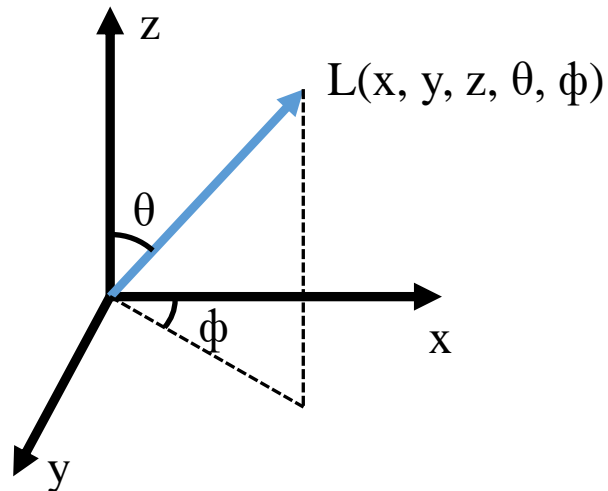


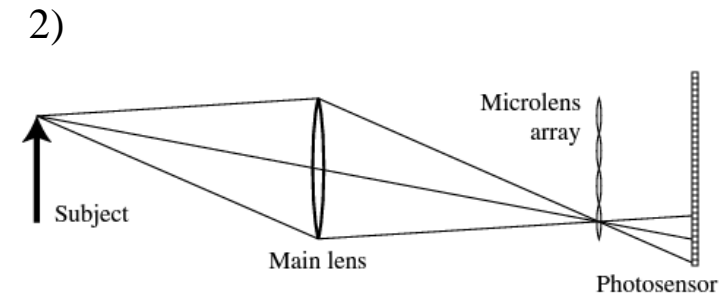
Light field

Information of ray (incoherent light)

- Three coordination (x, y, z)
- Two angle (θ , ϕ)
- Time (t)
- Radiance ($\text{W}/\text{m}^2/\text{sr}$)
- Polarization, color



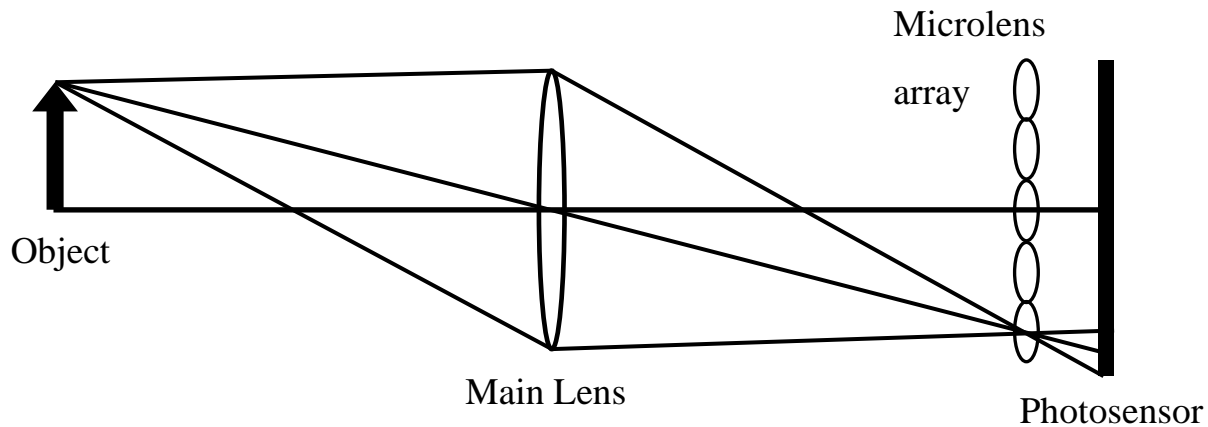
	Holography	Light field
Light source	coherent	Incoherent
View	continuous	Discrete (multi-view)
information	5D (Angle + position)	
Measurement	Interference measurement	MLA (micro lens array) or Multiple camera array
Noise	*technical noise + Speckle noise	*technical noise
*(photon and electronic noise from the recording sensor)		



1) ACM Trans. Graph. 24, 3 (July 2005), 765–776

2) Stanford University Computer Science Tech Report CSTR 2005-02

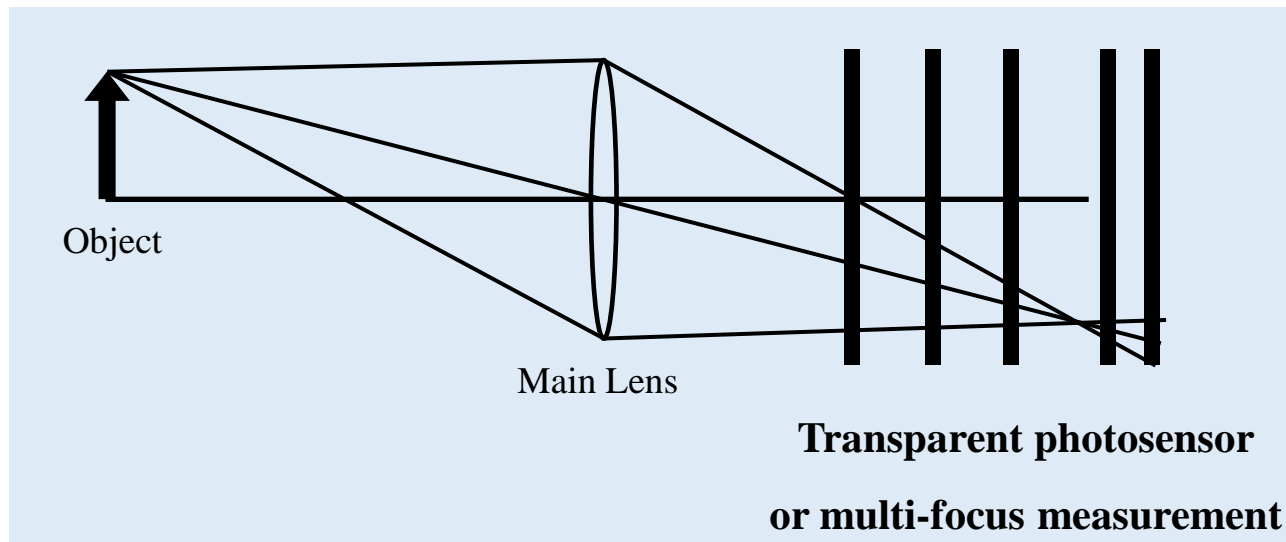
Multi-focus measurement



$$\text{Sensor resolution} = M \times M = M^2$$

$$\text{Micro lens array resolution} \\ = \text{Spatial resolution} = N \times N = N^2$$

$$\text{Angular resolution} = \text{Sensor resolution} / \text{Spatial resolution} \\ = M^2 / N^2$$

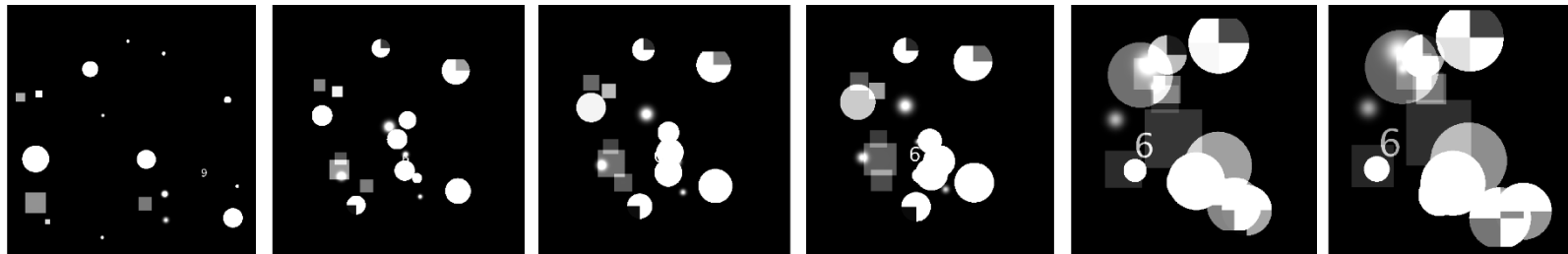


$$\text{Sensor resolution} = \text{Spatial resolution} \\ = M \times M = M^2$$

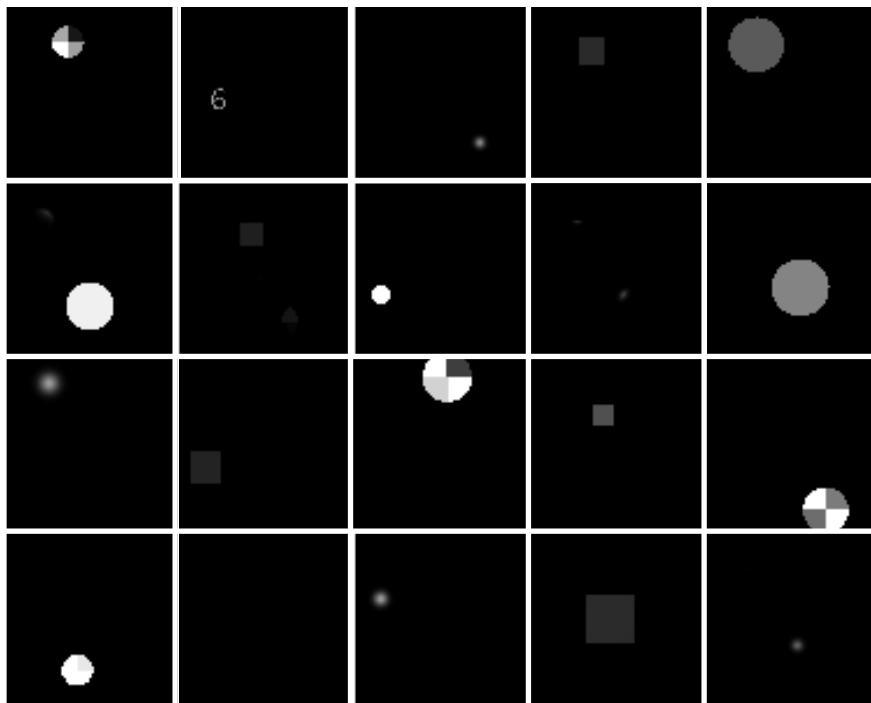
$$\text{Angular resolution} = 1 \sim M^2$$

Extraction algorithm of light field information from multi-plane images

Transparent sensors or multi-plane images



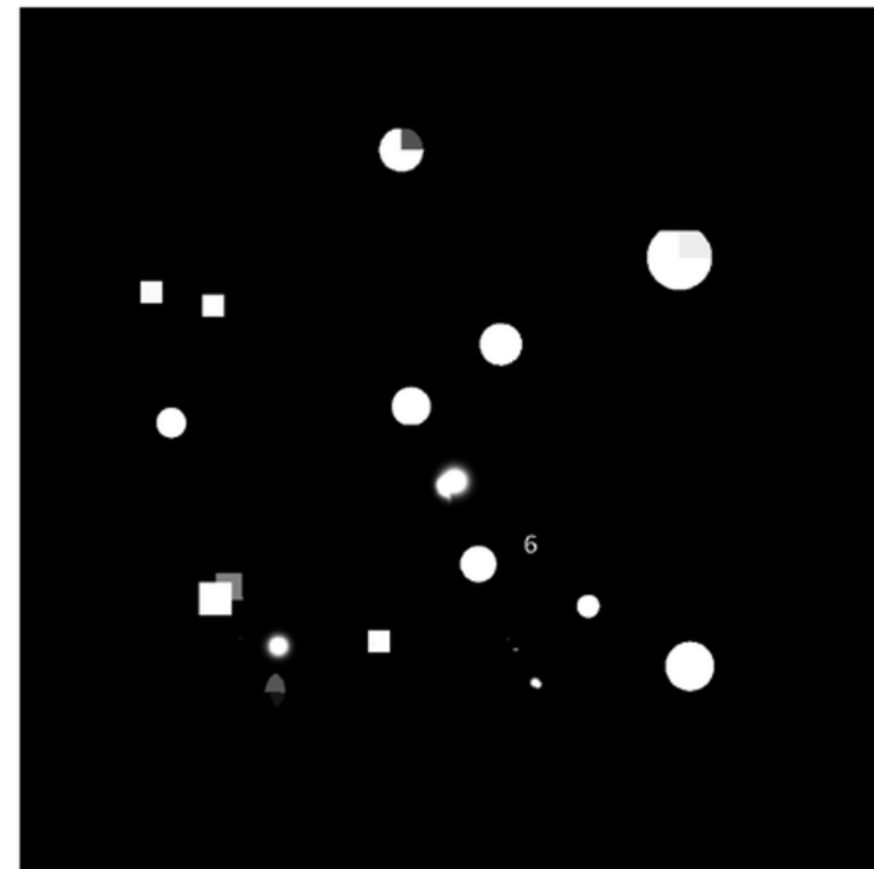
Deconvolution (multi-PSF, blind)



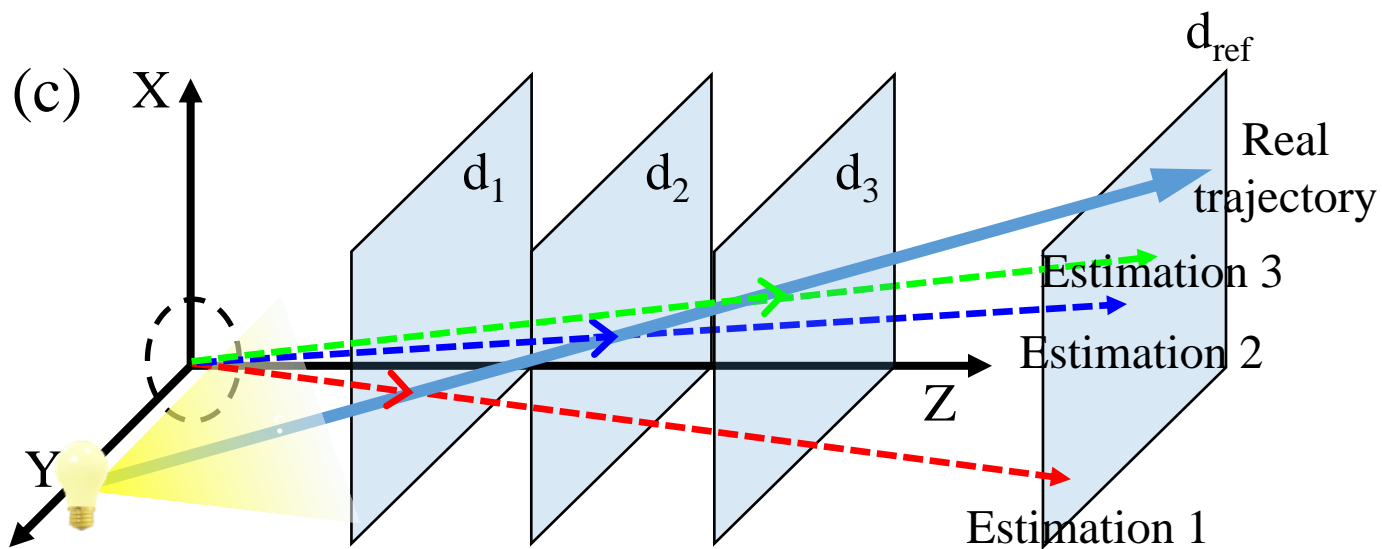
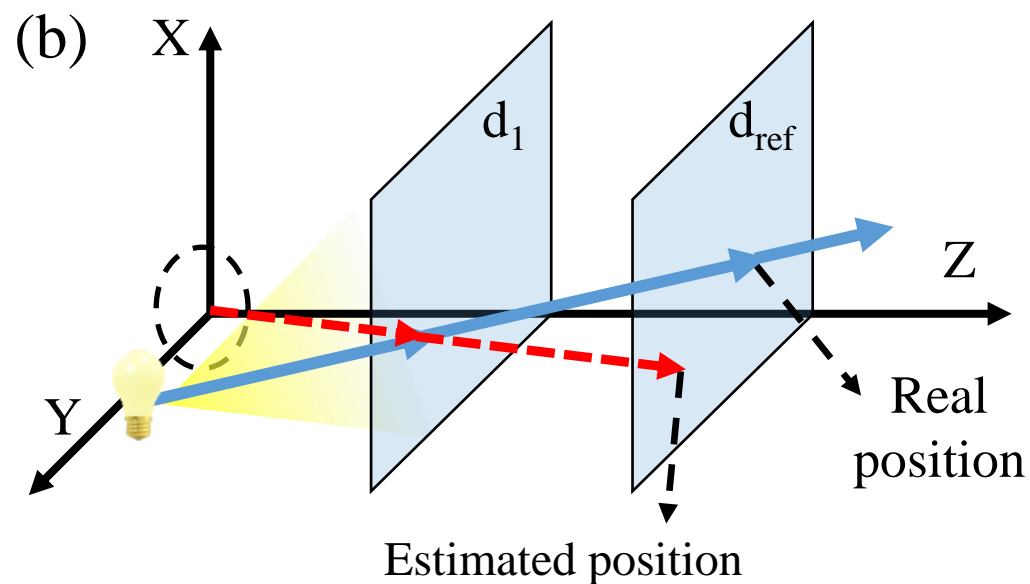
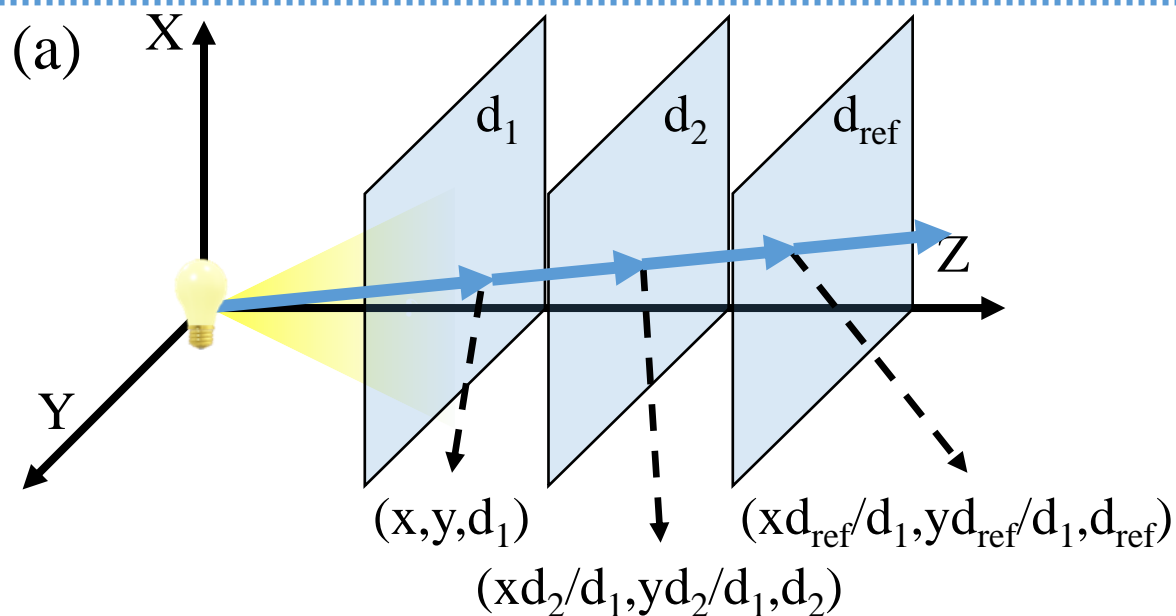
Coordination Transformation

Re-combination
Refocusing

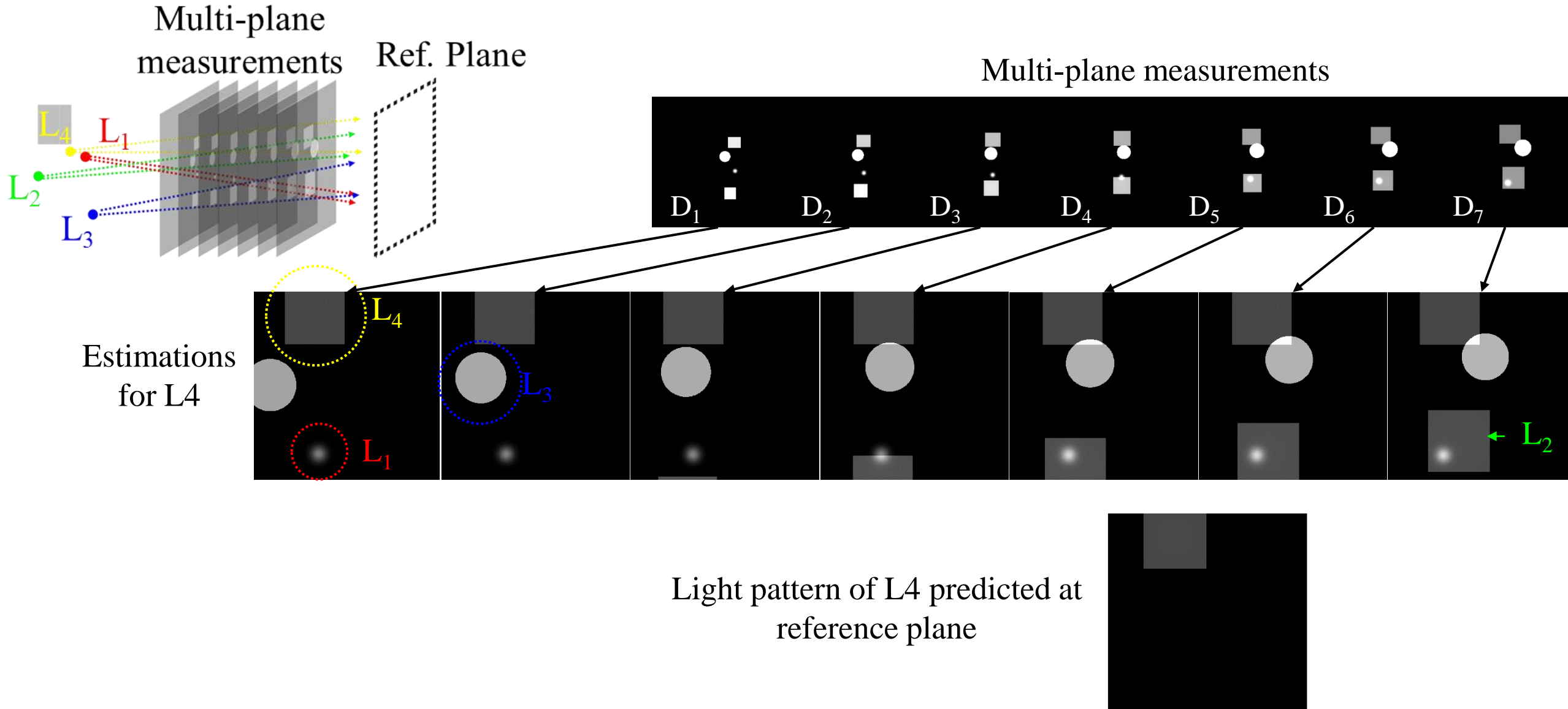
Refocusing



Measurements and predictions depending on the position of the light source

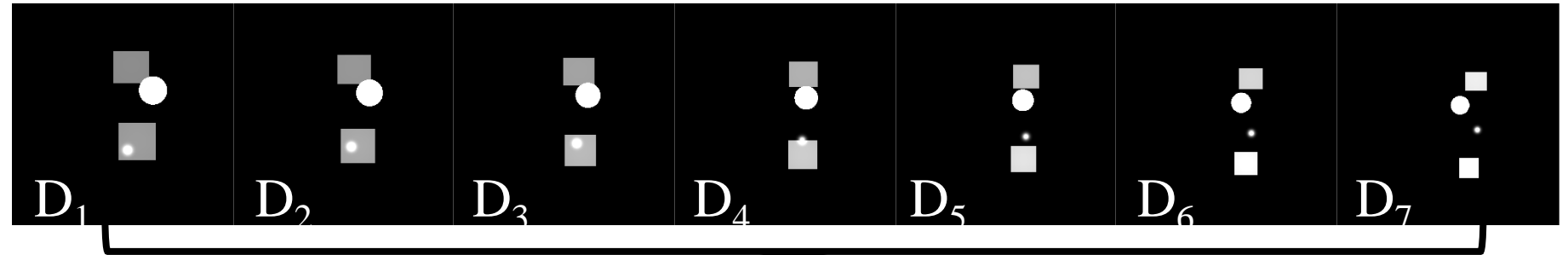


Measurements and predictions depending on the position of the light source

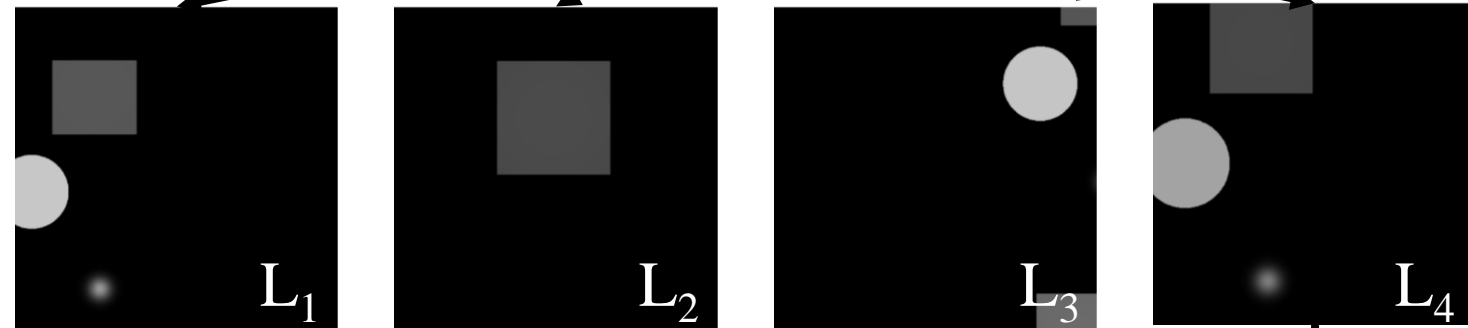


Measurements and predictions depending on the position of the light source

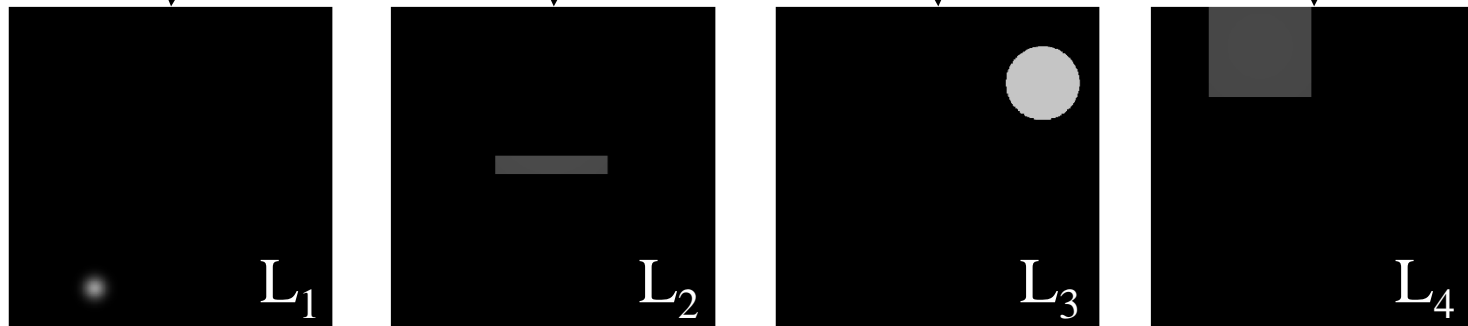
Multi-plane
measurements



Estimations at reference plane
for each light source

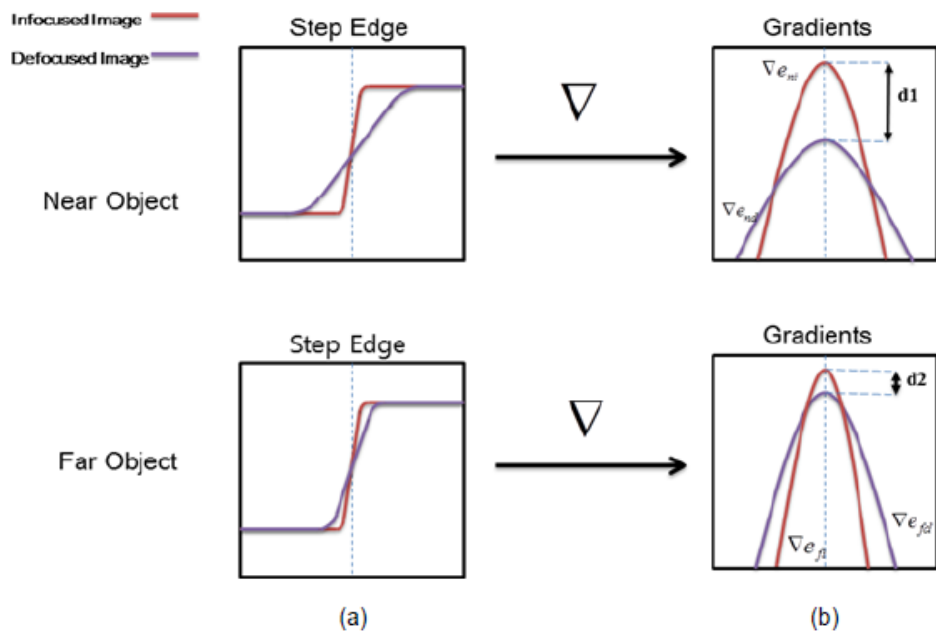


Extracted light information

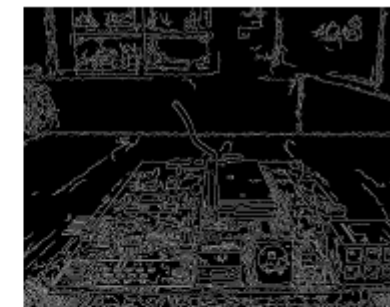
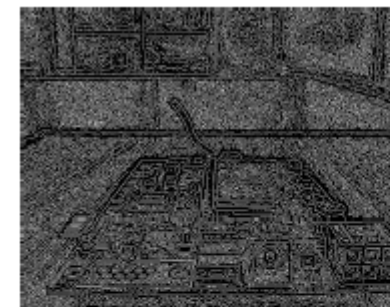


Computation reduction through depth estimation

If no light source is present, no static component is present in estimated images
-> Volume scanning (like confocal microscope) or depth estimation is needed

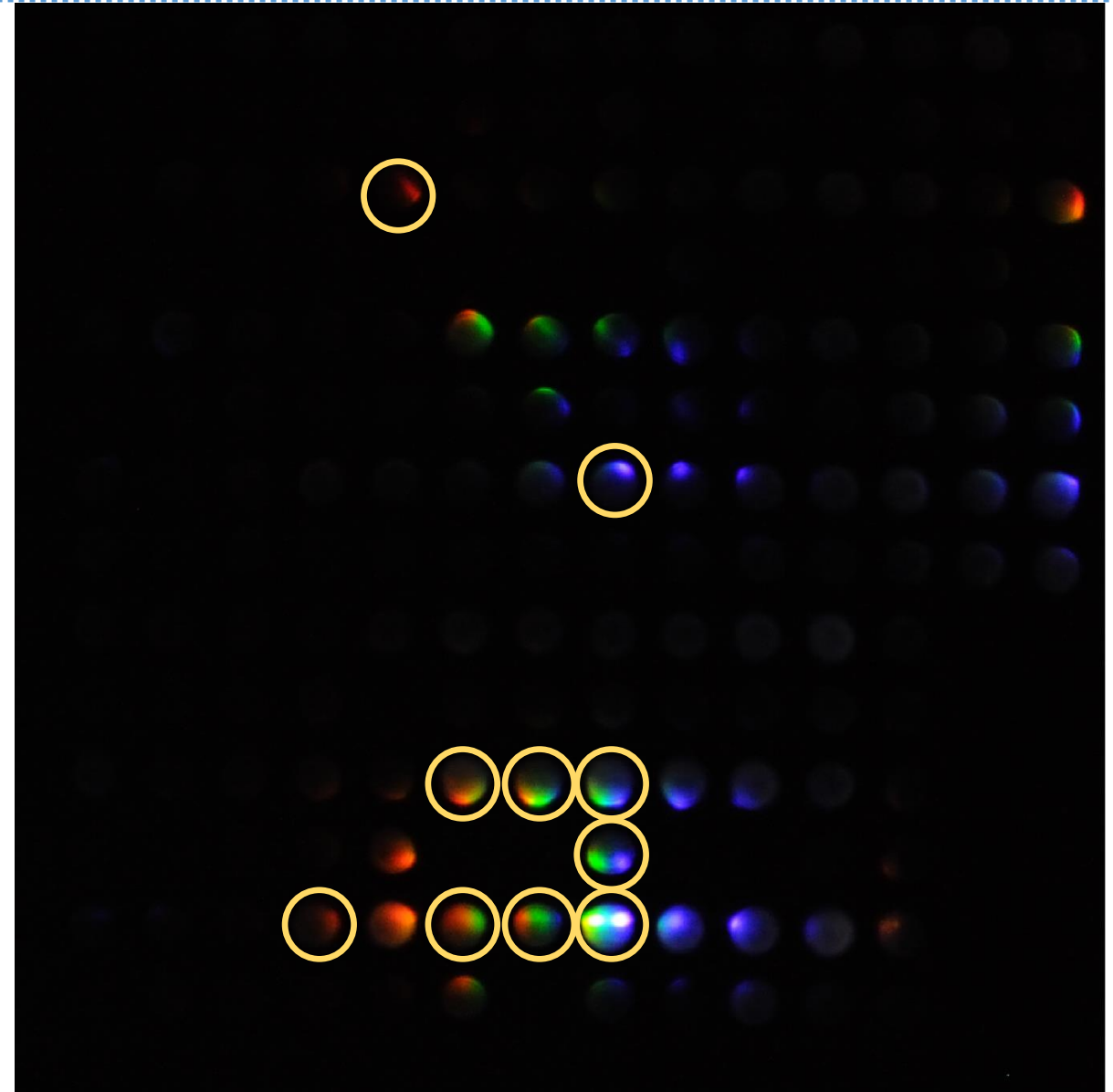
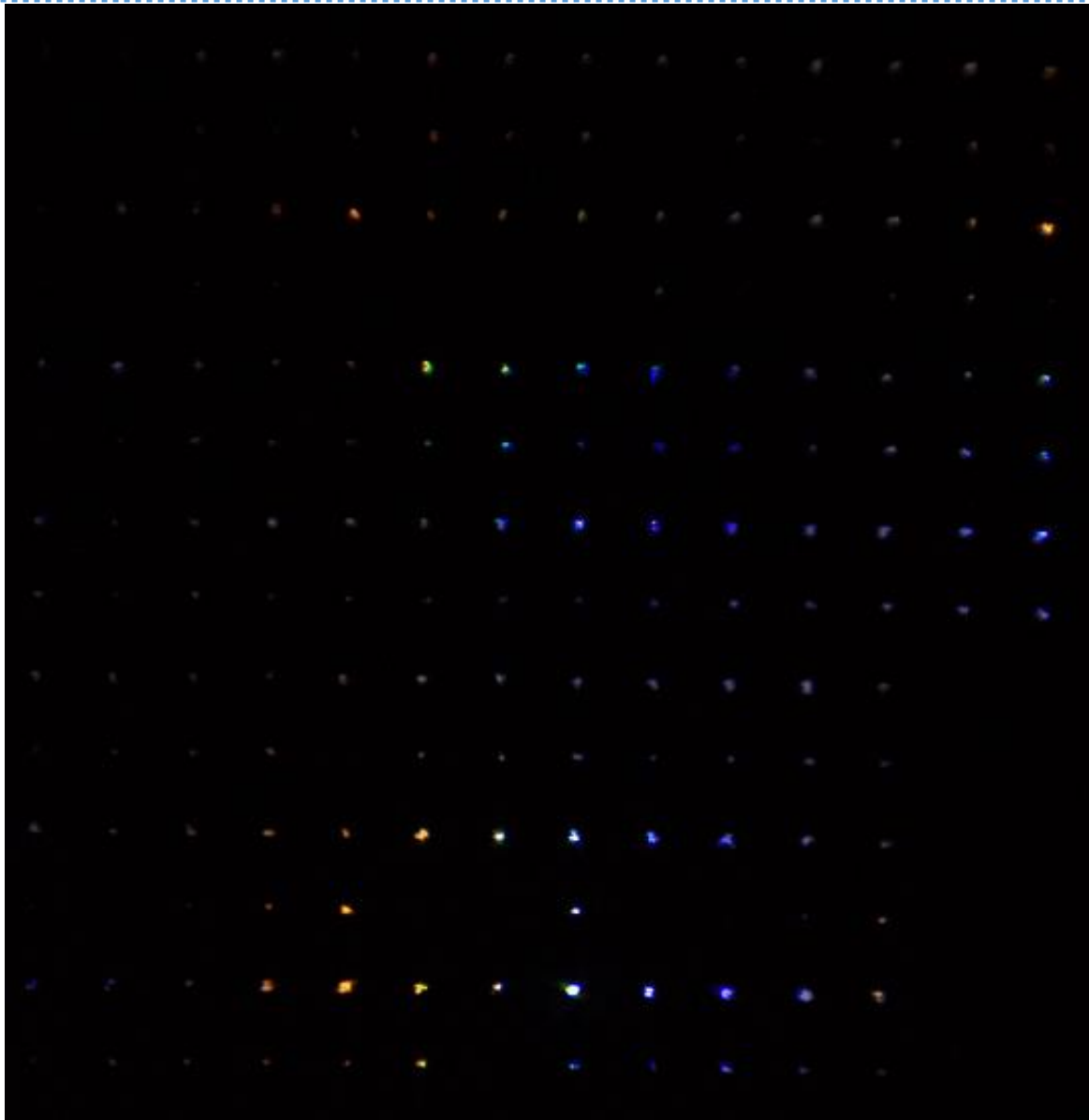


JBE Vol. 19, No. 3, May 2014

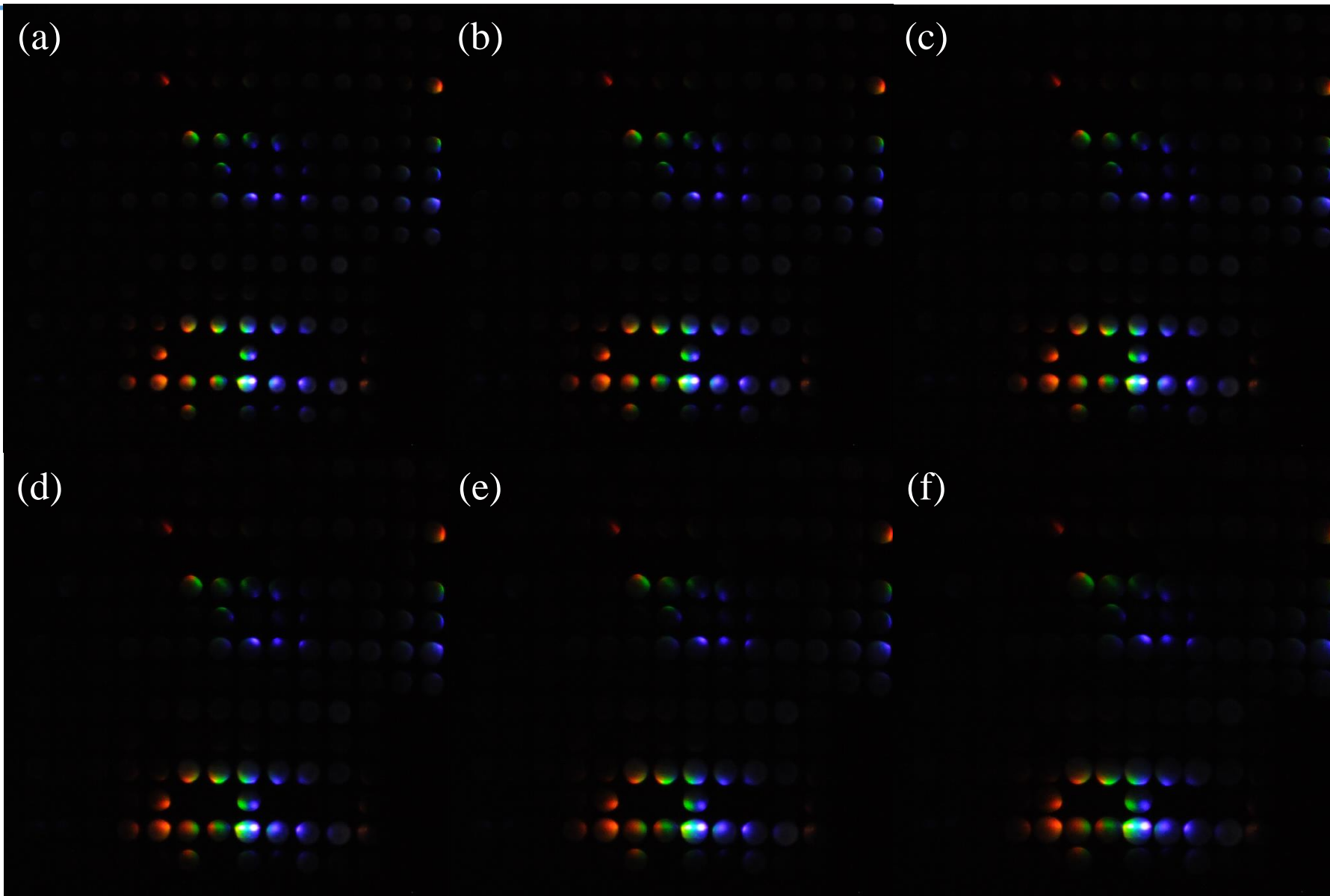


JBE Vol. 24, No. 2, March 2019

Extraction of light field information through multi-focus measurements

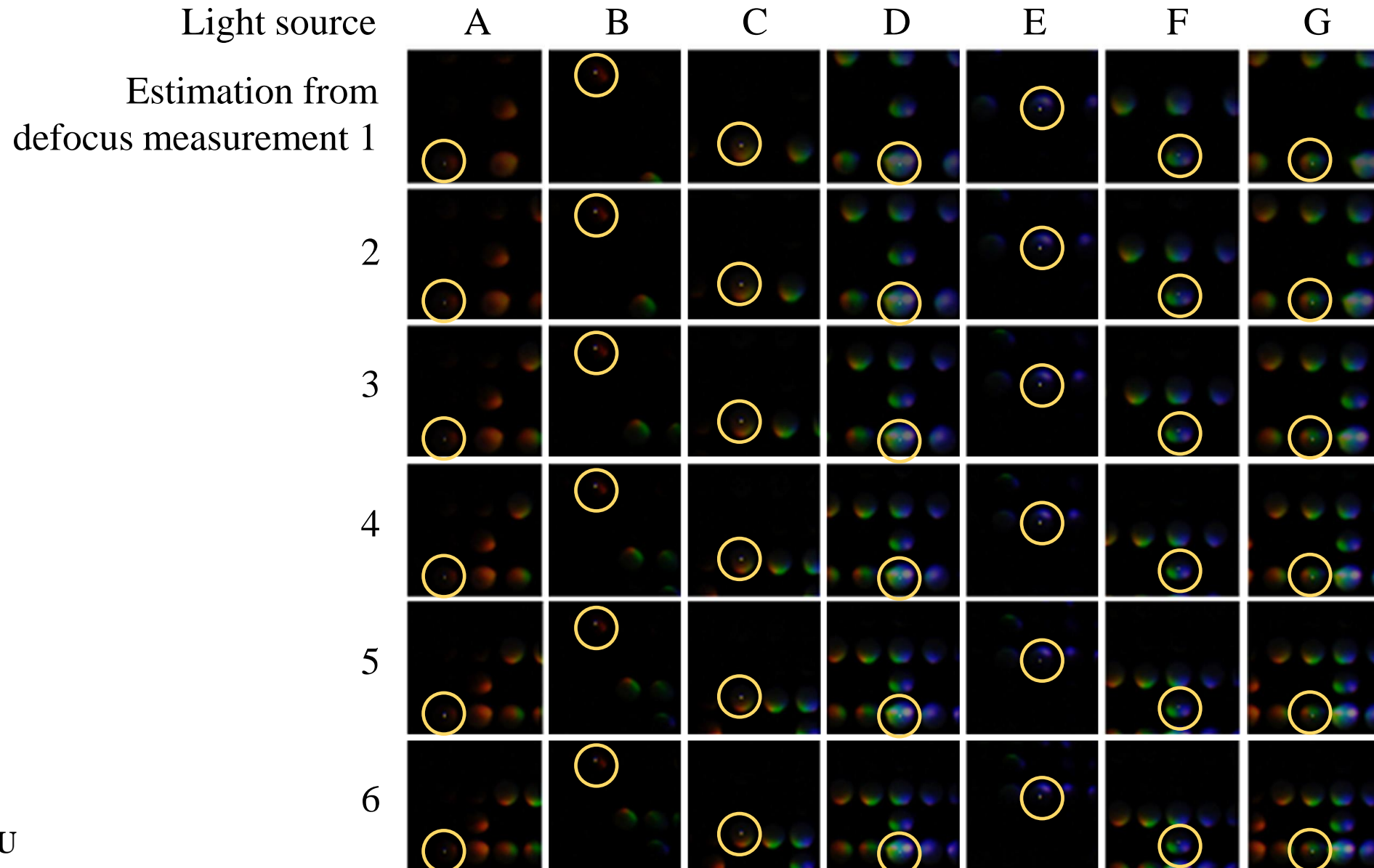


Extraction of light field information through multi-focus measurements

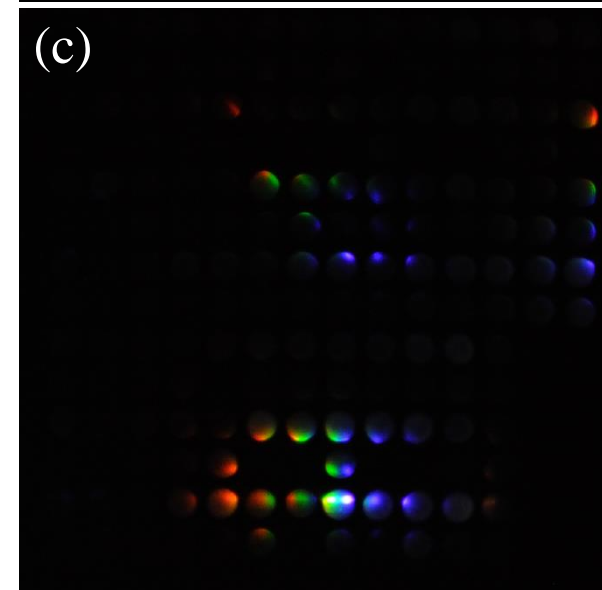
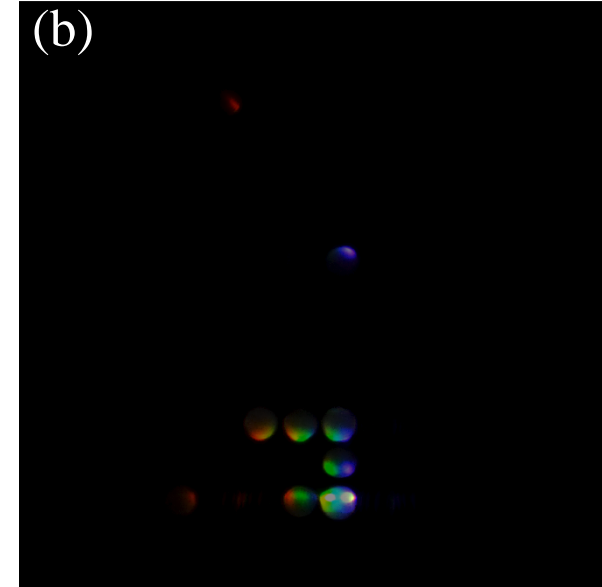
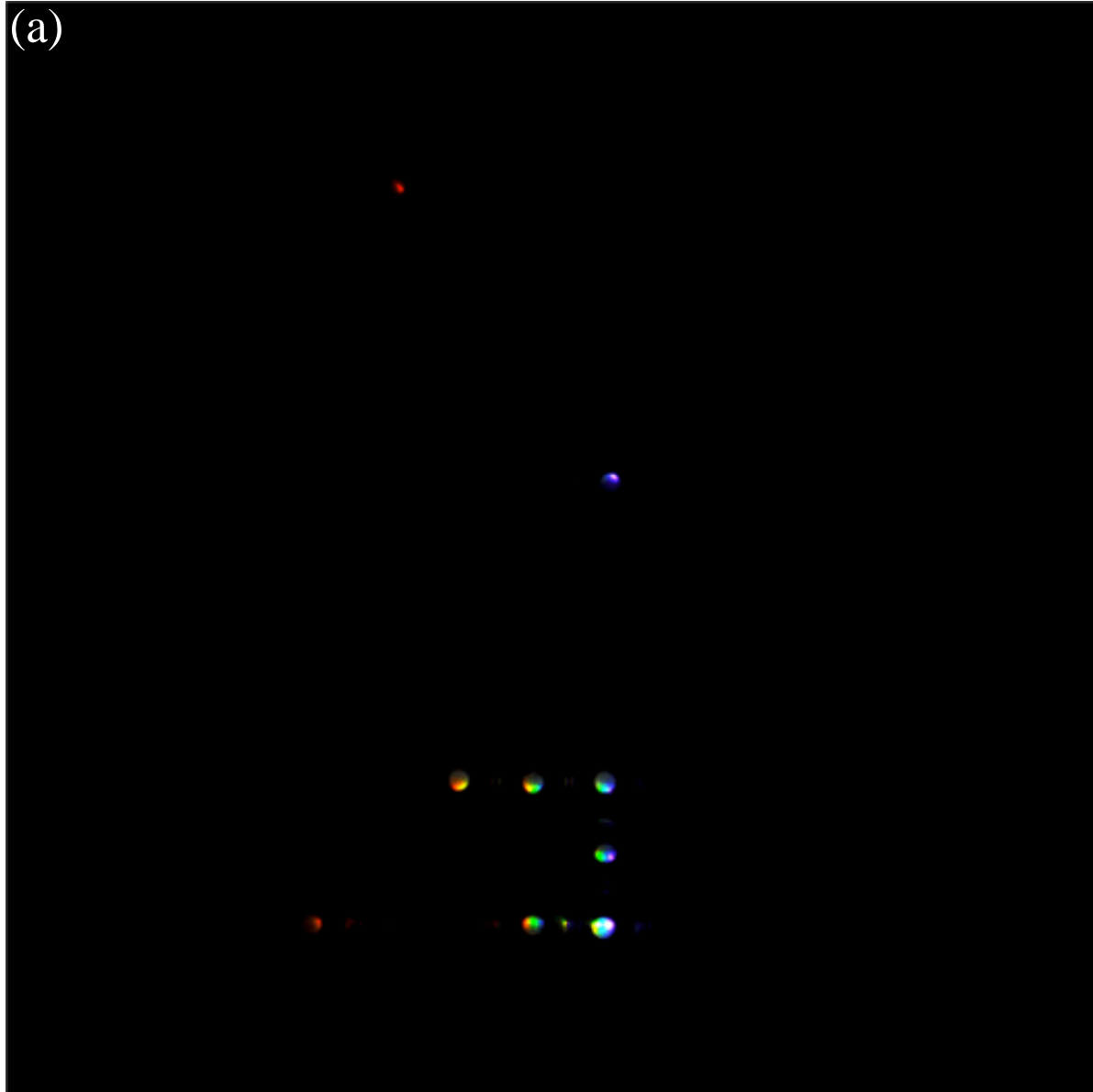


Defocus
Measurement 1 ~6
+
Camera
information
+
(Location of
Interest)


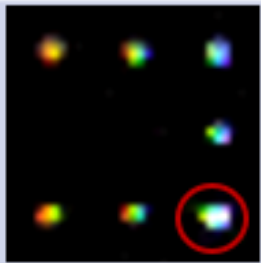
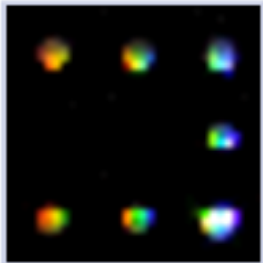
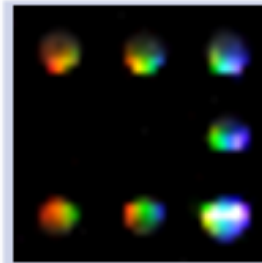
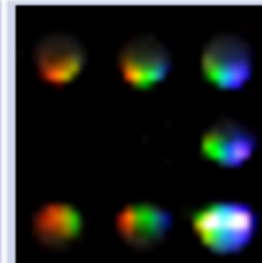
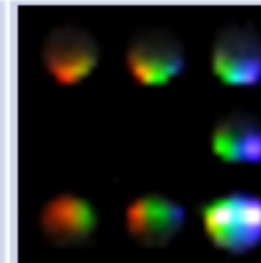
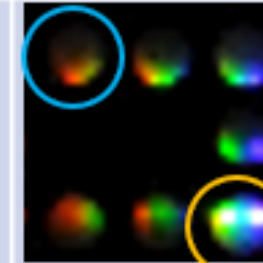
Extraction of light field information through multi-focus measurements



Extraction of light field information through multi-focus measurements



Extraction of light field information through multi-focus measurements

상대 거리 (A.U.)	36	48	56	64	74	82	90
실제 측정							
Re- focusing	