

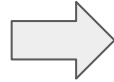
# UrbanMindscape: Bridging the Subjective and Objective Perception in Proximate Sensing

Keywords: Urban Perception; Semantic Segmentation; Street View Images; Convolutional Neural Network (CNN); Deep Learning

Ling Chen, MUSA650 Final Project

# BACKGROUND

Street View  
Images(SVI) have  
been a valuable  
resource in  
different contexts.



Urban Analysis of the Built Environment

Infrastructure Management

Environmental Monitoring

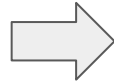
Real Estate and Property Management

Public Safety and Security

Social and Economic Research

# BACKGROUND

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## Urban Analysis of the Built Environment

Create visual representations of human perceptions and the physical characteristics of urban environments by leveraging deep learning techniques.

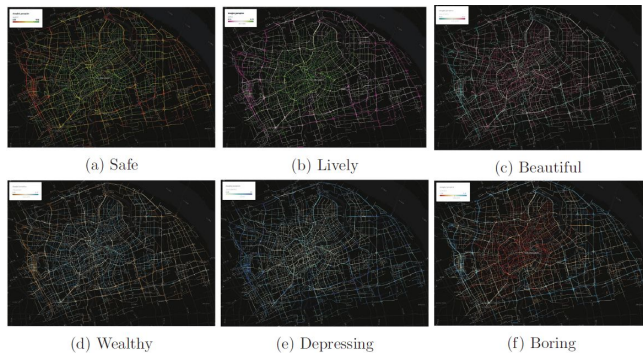
Objective

Subjective

A comprehensive understanding  
of urban spaces

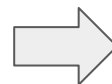
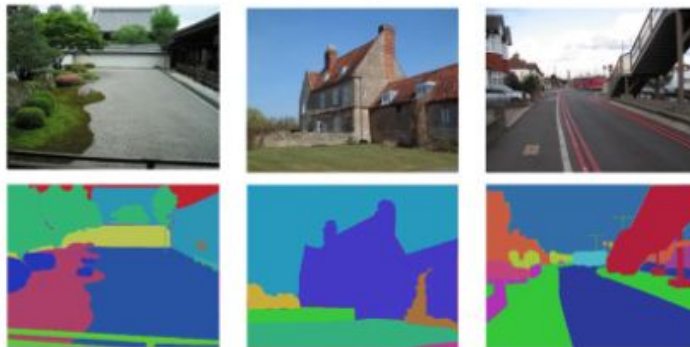
# Background

Subjective



+

Objective



Urban  
Perception

Human Perception Score

Proximate Sensing



# Background

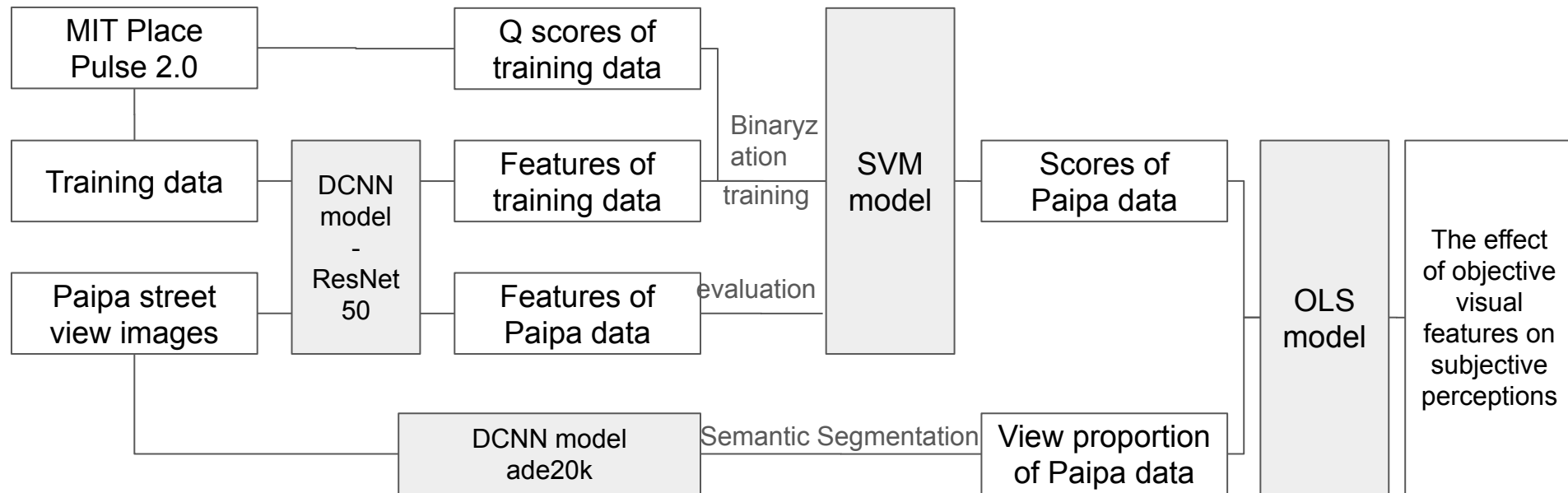
## MIT Place Pulse 2.0

Continent	#Cities	#Images
Asia	7	11,342
Africa	3	5,069
Australia	2	6,082
Europe	22	38,636
North America	15	33,691
South America	7	16,168
Total	56	110,988

The user interface of the MIT Place Pulse data collection platform. Participants are asked to choose one of the two images in response to one of the six questions. Millions of human perception responses for the images have been collected.



# Methods



# Experiment

## Study Area:

**Train:** MIT Place Pulse 2.0 dataset

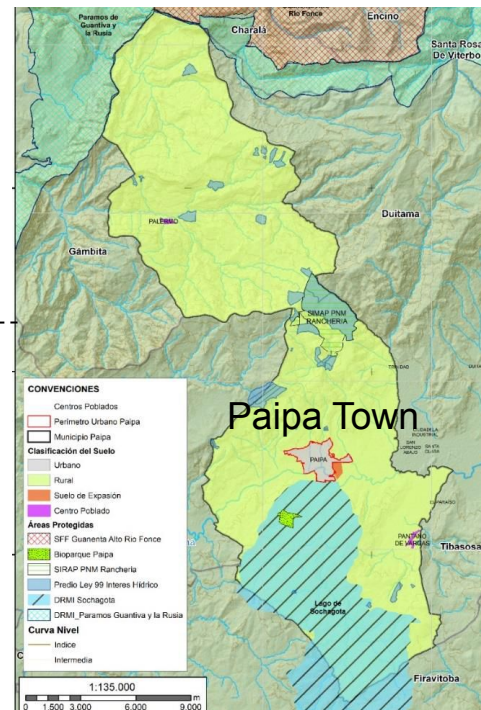
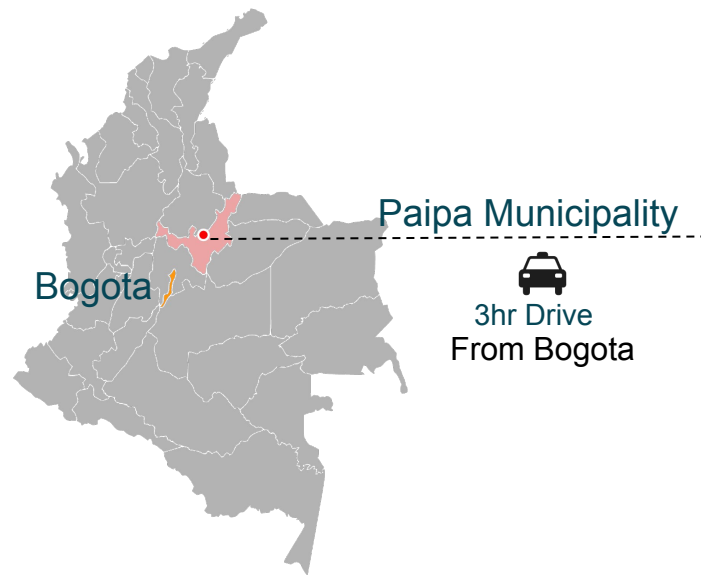
**Test:** Paipa Town, Colombia

## Dataset:

MIT Place Pulse 2.0 street view images across the world

MIT Place Pulse 2.0 Q scores of SVI in six human perceptions

Paipa street view images(10m distance)



# Experiment

To avoid introducing noise and error as much as possible, I followed the paper reference here and selected representative positive/negative samples from the whole dataset to use for the training task.

$$y_i^v = \begin{cases} -1 & \text{if } Q_i^v < \mu_v - \delta\sigma_v \\ 1 & \text{if } Q_i^v > \mu_v + \delta\sigma_v \end{cases}$$

- Safe 6.3
- Beautiful 5.3
- Wealthy 5.5
- Lively 6.0
- Boring 2.3
- Depressing 1.6

1

1

1

1

-1

-1

Binaryzation

location_id	Q	trueskill.stds.-1	study_question	image_id	features	Q_label
0	513e6df2fdc9f0358700c383	20.592330	safer	513e6df2fdc9f0358700c383	[0.22940833866596222, 1.0244624614715576, 0.01...	-1.0
4	5140cc3efdc9f04926002d59	28.707450	safer	5140cc3efdc9f04926002d59	[0.12468238919973373, 0.5190224647521973, 0.04...	1.0
5	50f5ec0dfdc9f065f0008640	20.298309	safer	50f5ec0dfdc9f065f0008640	[0.06582643836736679, 0.41787010431289673, 0.0...	-1.0
6	50f60121beb2fed6f80001b8	18.482701	safer	50f60121beb2fed6f80001b8	[0.34781795740127563, 0.6622889041900635, 0.12...	-1.0
8	5142183ffdc9f04926008100	27.814428	safer	5142183ffdc9f04926008100	[0.12155959755182266, 0.771874725818634, 0.020...	1.0
...	...	...	...	...	...	...
19993	50f5e70dfdc9f065f0007031	28.091575	safer	50f5e70dfdc9f065f0007031	[0.4073934257030487, 0.5427781343460083, 0.159...	1.0
19995	50f439edfdc9f065f0002d42	16.917069	safer	50f439edfdc9f065f0002d42	[0.2706283926963806, 0.8877367377281189, 0.329...	-1.0
19996	50f42eabfdc9f065f00022d3	33.181343	safer	50f42eabfdc9f065f00022d3	[0.21051648259162903, 1.1483752727508545, 0.06...	1.0
19997	5140cc37fdc9f04926002d47	20.803571	safer	5140cc37fdc9f04926002d47	[0.057956207543611526, 0.8228529095649719, 0.0...	-1.0
19999	513d5787fdc9f0358700319e	20.646238	safer	513d5787fdc9f0358700319e	[0.3766400218009949, 1.0521074533462524, 0.068...	-1.0

10922 rows × 7 columns

# Street Perception Analysis: Subjective Perceptions

Which place looks **safer** ?

Which place looks **safer**?

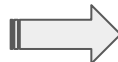
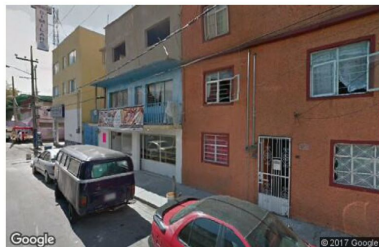
Which place looks **livelier**?

Which place looks **more boring**?

Which place looks **wealthier**?

Which place looks **more depressing**?

Which place looks **more beautiful**?



Training data: 110,988 samples from 56 cities

Dubey, A., Naik, N., Parikh, D., Raskar, R., & Hidalgo, C. A. (2016). Deep learning the city: Quantifying urban perception at a global scale. European conference on computer vision (pp. 196–212). Springer.

Testing data: 15,000 samples in Paipa

This model answers question:

**Is this place safe/ lively/ beautiful/  
wealthy/ boring/ depressing?**



# Street Perception Analysis: Safe ●



Background

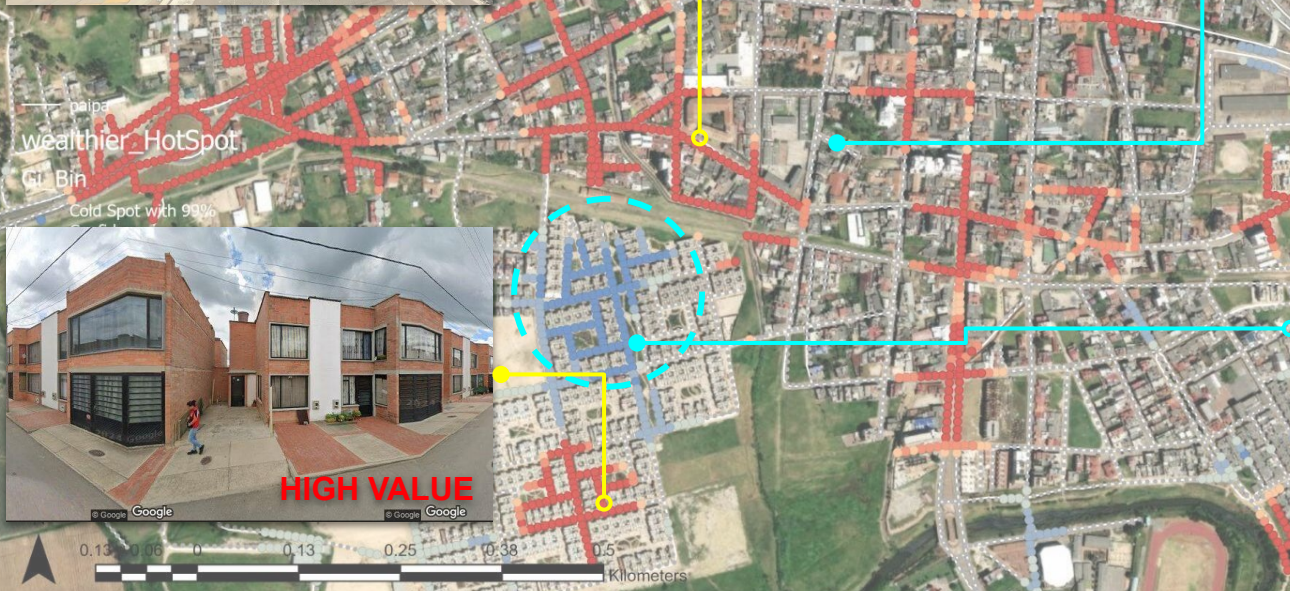
Method

Result: Human Perception - Semantic Segmentation

Conclusion



# Street Perception Analysis: Wealthy



Source: Esri, Maxar Earthstar Geographics, and the GIS User Community

Background

Method

Result: Human Perception - Semantic Segmentation

Conclusion



# Street Perception Analysis: Lively ●



Background

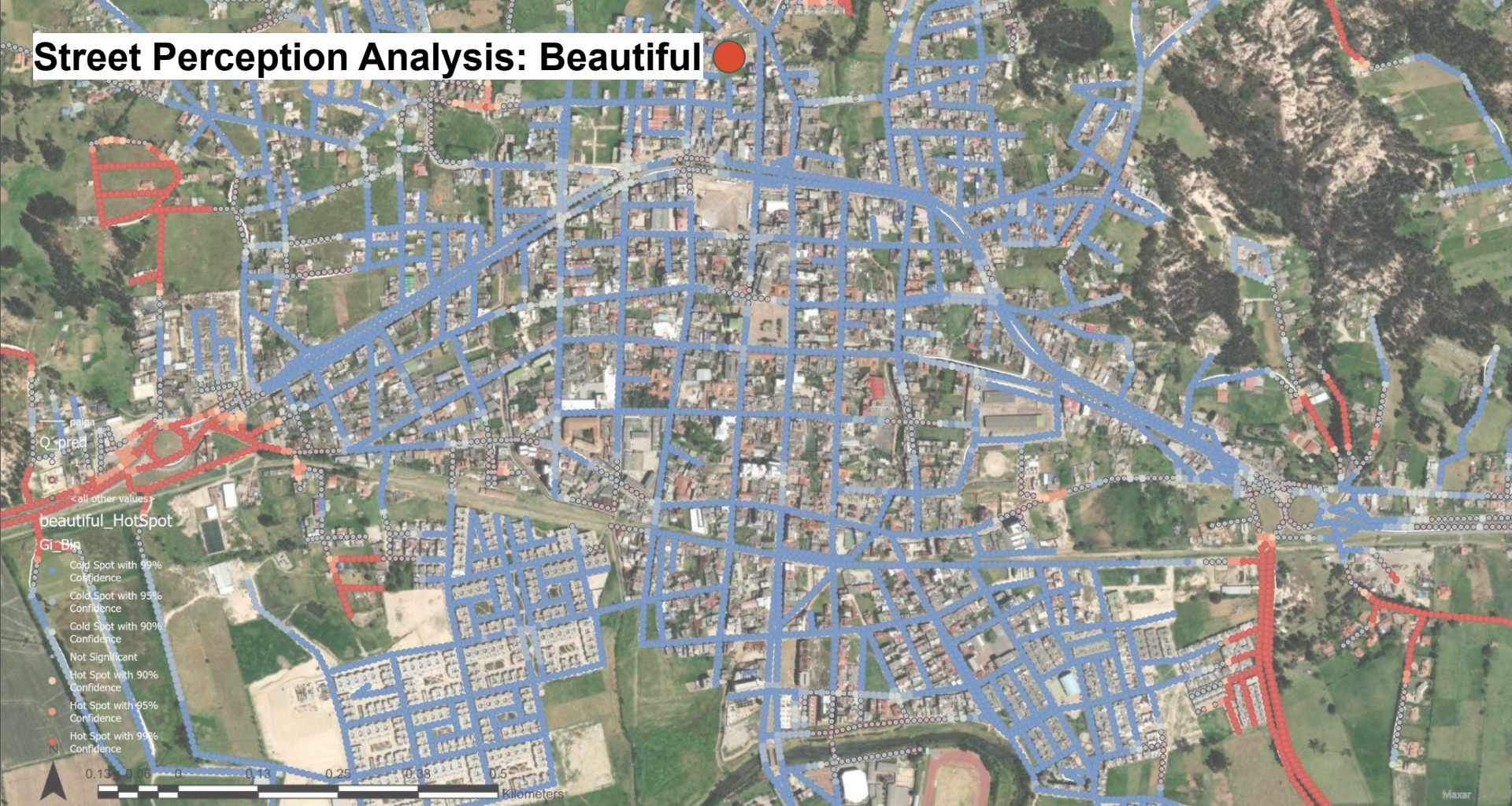
Method

Result: Human Perception - Semantic Segmentation

Conclusion



# Street Perception Analysis: Beautiful ●



Background

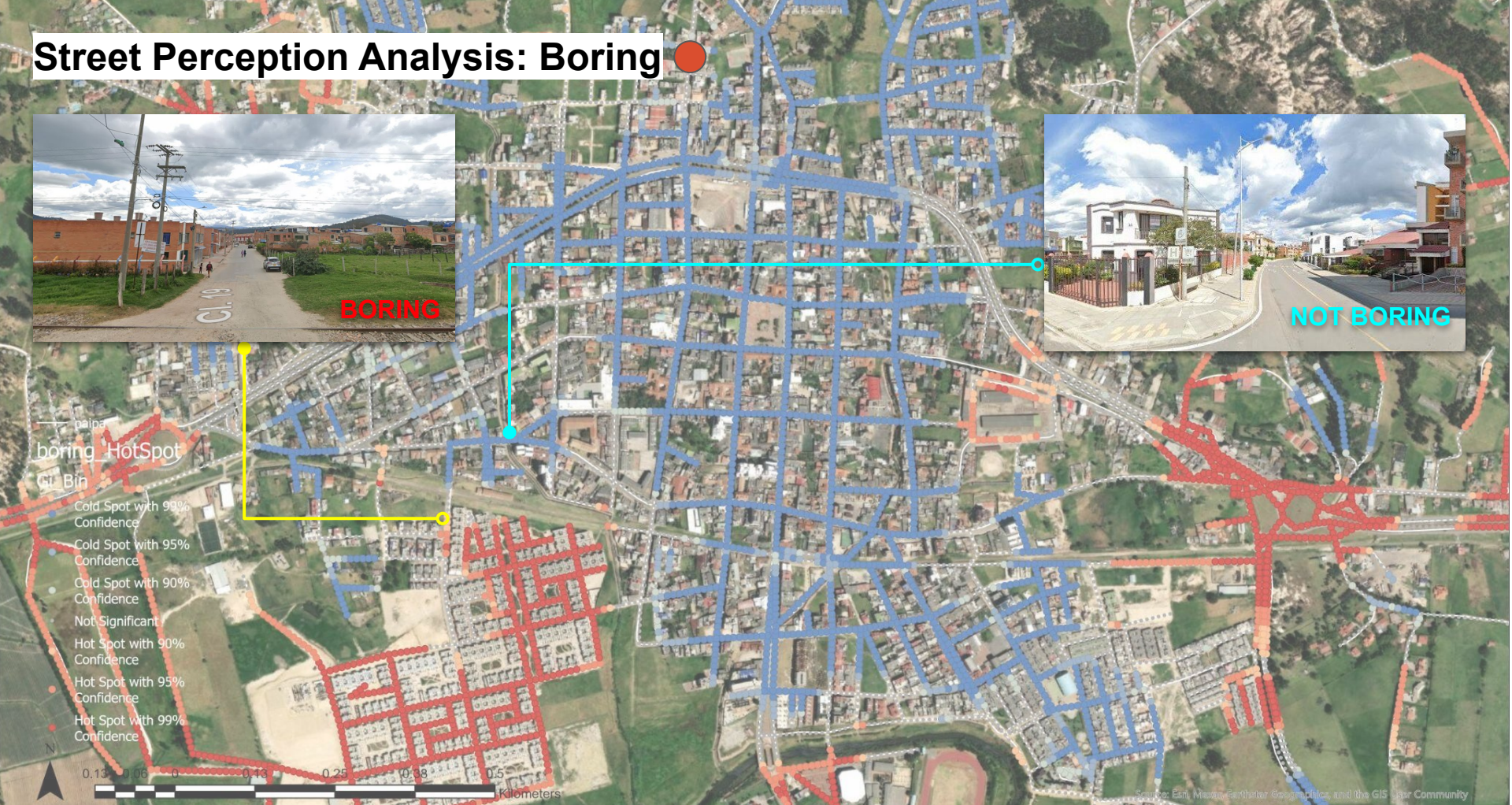
Method

Result: Human Perception - Semantic Segmentation

Conclusion



# Street Perception Analysis: Boring



Background

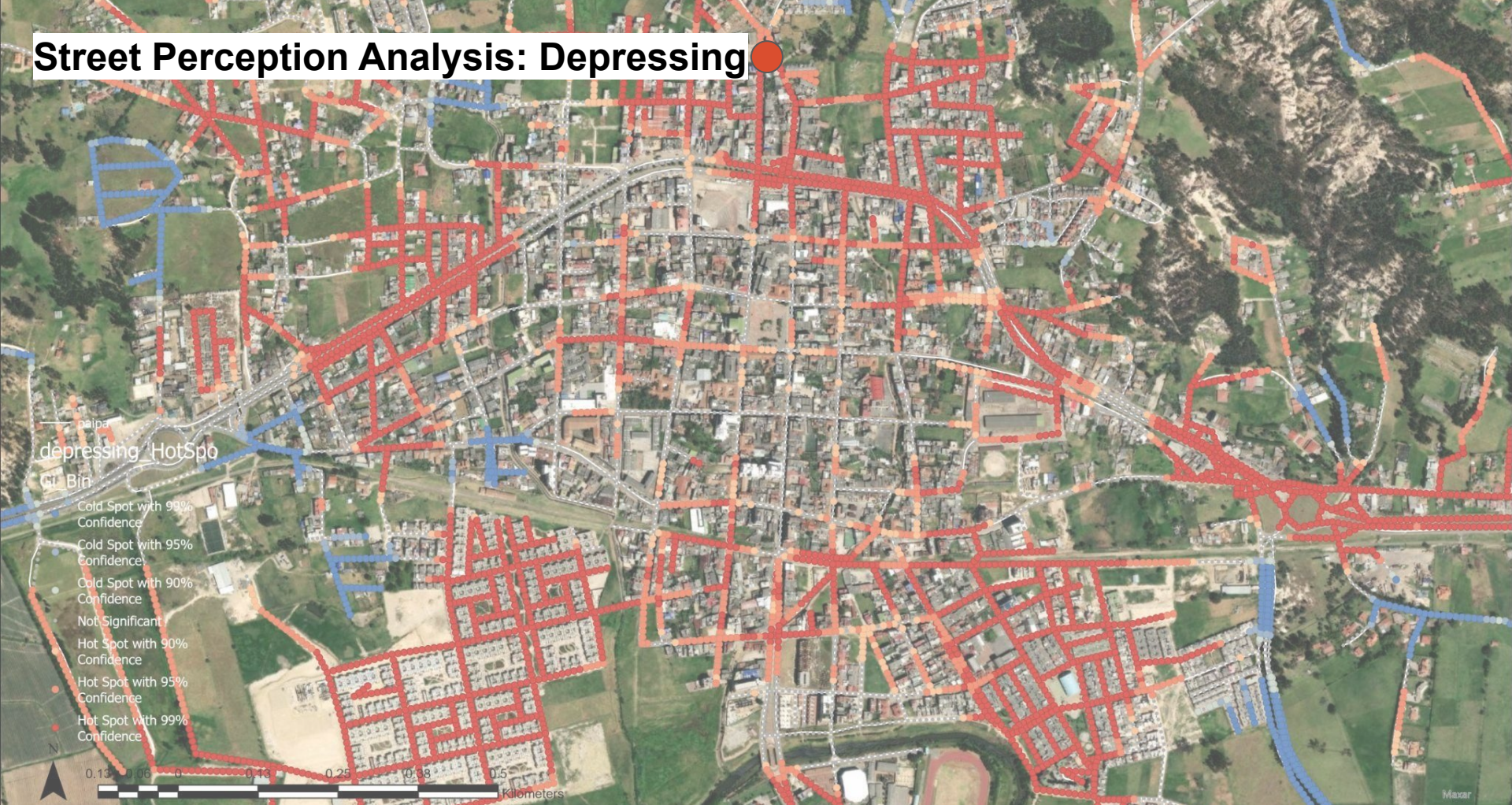
Method

Result: Human Perception - Semantic Segmentation

Conclusion



# Street Perception Analysis: Depressing



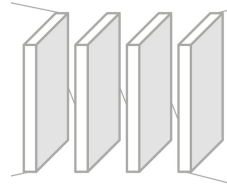
Background

Method

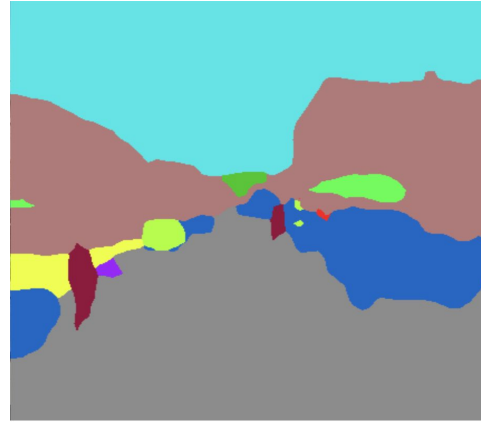
Result: Human Perception - Semantic Segmentation

Conclusion

# Street Perception Analysis: Objective Perception



Semantic Segmentation



- wall 0.0013
- building 0.1071
- sky 0.1700
- tree 0.2843
- road 0.2251
- grass 0.1020
- sidewalk 0.0033
- plant 0.0001
- car 0.0973
- sign 0.0035
- stairs 0.0002
- van 0.0058

building
car
grass
plant
road
sidewalk
signboard
sky
stairs
tree
van
wall

What percentage of the vision is building/car/tree/sky/road...?



# Street Perception Analysis: Objective Perception

## Classes related to urban space

Idx	Name
1	wall
2	building;edifice
3	sky
4	floor;flooring
5	tree
7	road;route
9	windowpane;window
10	grass
12	sidewalk;pavement
13	person;individual;someone;somebody;mortal;soul
18	plant;flora;plant;life
21	car;auto;automobile;machine;motorcar
26	house
44	signboard;sign
54	stairs;steps
103	van



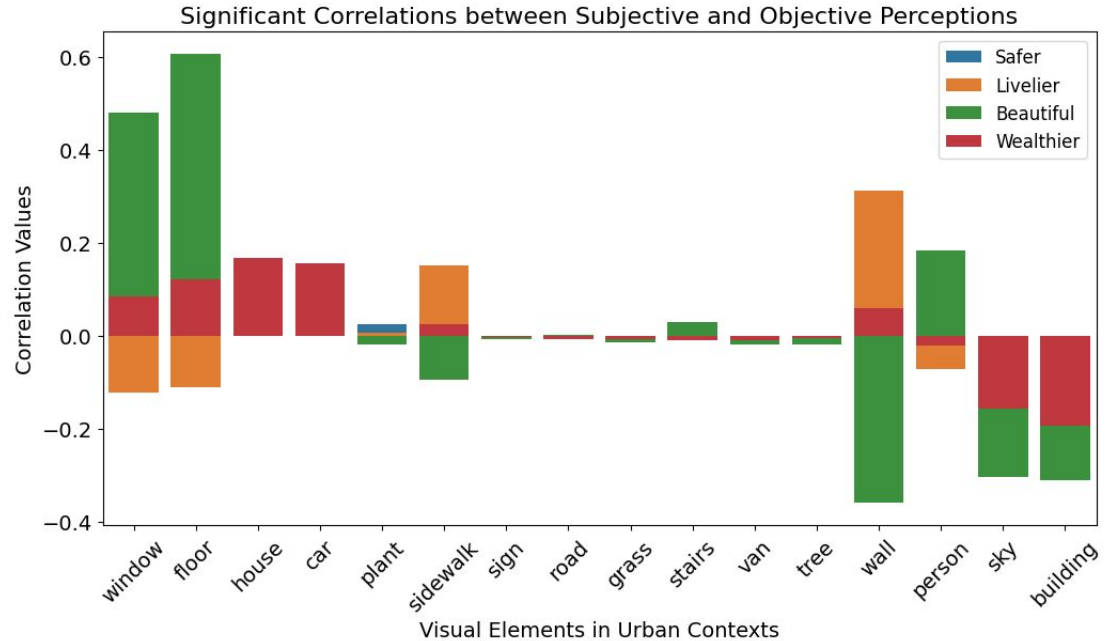
# Street Perception Analysis: Objective Perception

Visual  
Proportion



Perceptual  
precognition

Multivariable  
Linear  
Regression  
Analysis



How does the proportion of building/car/tree/sky/road affect the feeling of safe/ lively/ beautiful/ wealthy/ boring/ depressing.

# Street Perception Analysis: Objective Perception

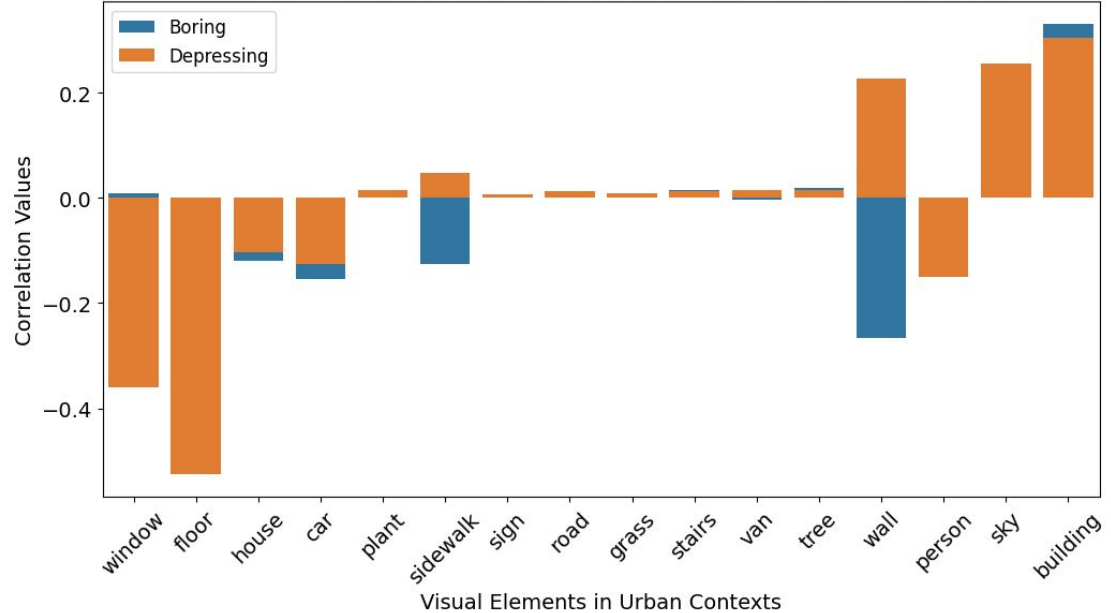
Visual  
Proportion



Perceptual  
precognition

Multivariable  
Linear  
Regression  
Analysis

Significant Correlations between Subjective and Objective Perceptions



How does the proportion of building/car/tree/sky/road affect the feeling of safe/ lively/ beautiful/ wealthy/ boring/ depressing.

# Street Perception Analysis: Design Solution Guidelines

Unsafe places

Unbeautiful places

Unlively places

Low-value places

Boring places

Depressing places

- **Enhancing green space**

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- **Increasing open public spaces**

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- **Building Complete Streets**

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- **Promoting quality housing**

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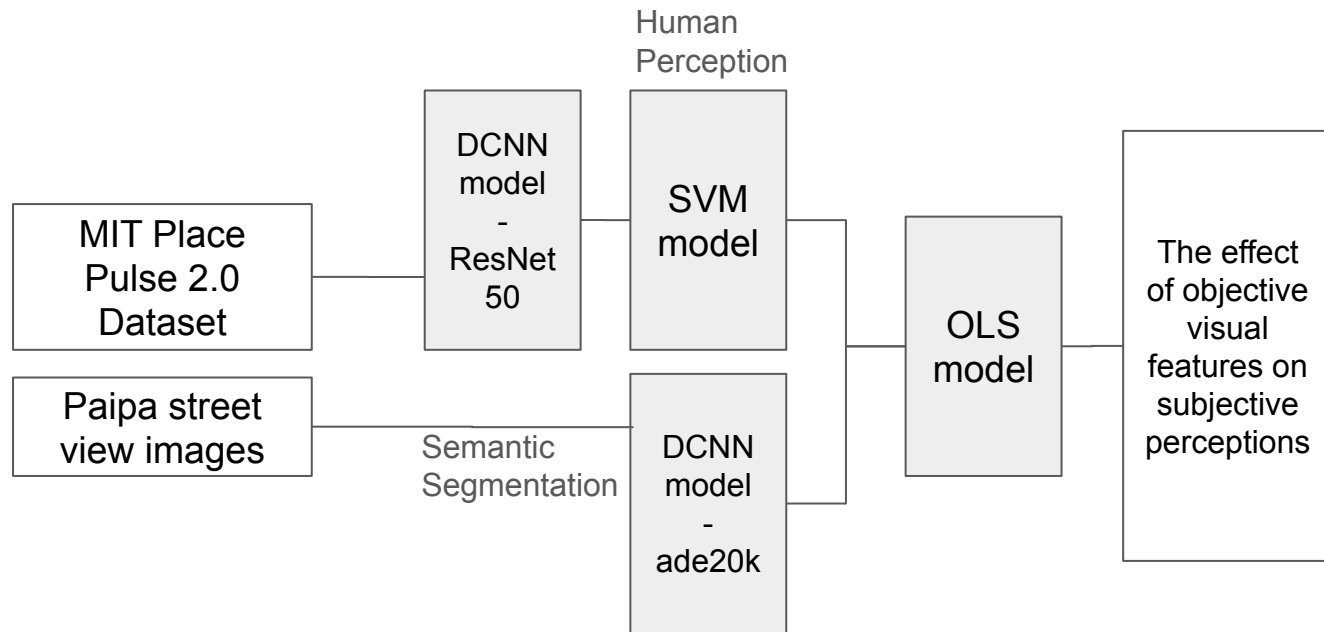
- **Enhancing street walkability**

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- **Reducing enclosed spaces**



# Conclusion



## Next Step

Generate a real image of SVI that is a safe/lively/beautiful/wealthy /boring/depressing place

Select the image closest to the center of the cluster of safe/lively/beautiful/wealthy /boring/depressing place